



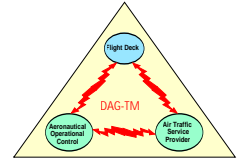
Terminal Arrival: Self-Spacing for Merging and In-Trail Separation

(Concept Element 11)

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Self-spacing for Merging and In-trail Separation



Problem:

- Excessive spacing buffers on final approach reduce arrival throughput and airport capacity

Solution:

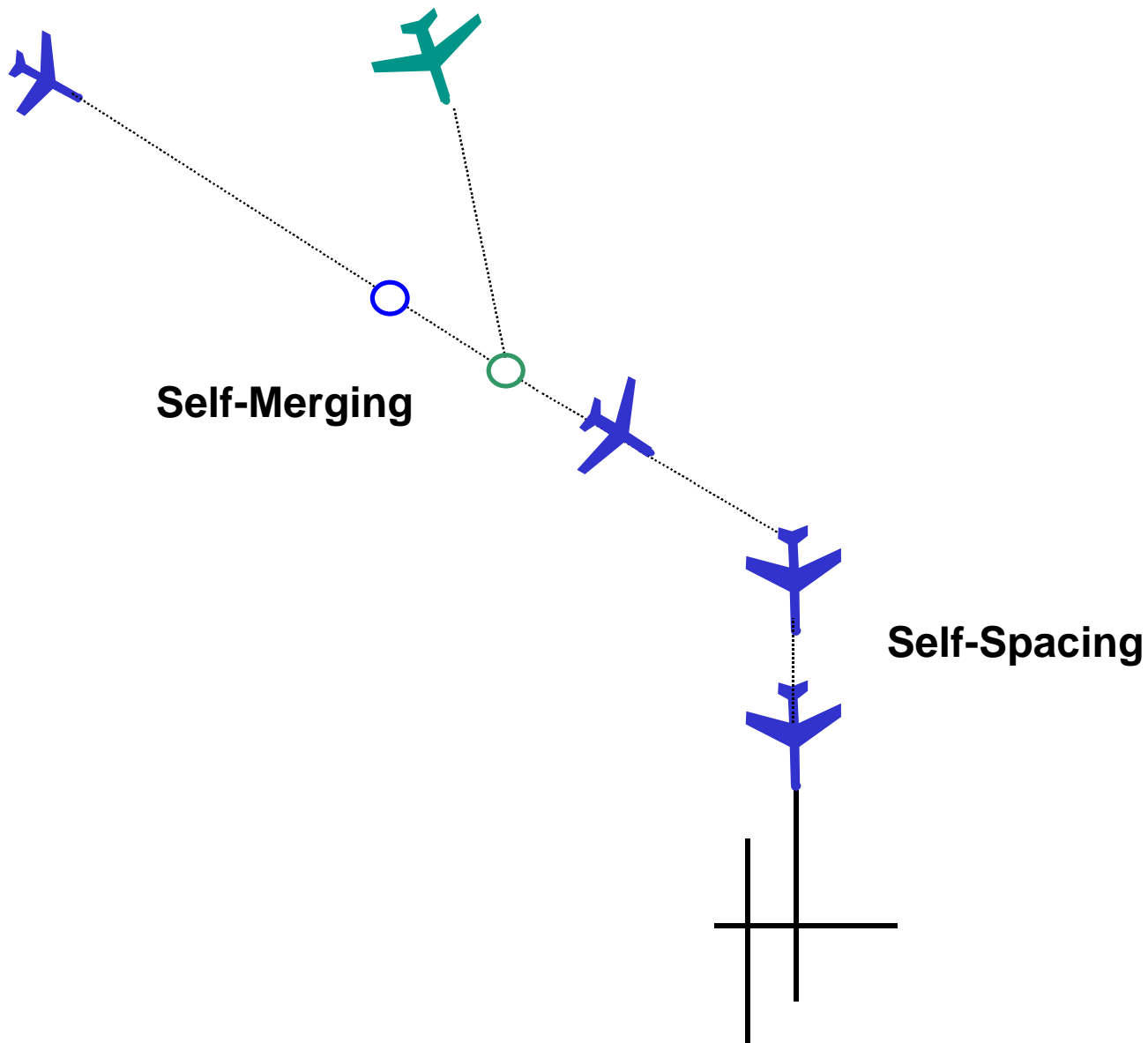
- Appropriately equipped aircraft are cleared to maintain separation relative to other aircraft during both instrument and visual conditions
 - flight deck displays and guidance for:
 - Merging and conflict detection/resolution
 - Fine tuning of fixed-time spacing

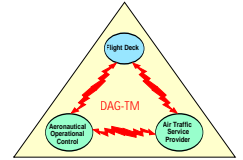
Benefits:

- Increased arrival throughput
- Enhanced controller & pilot shared understanding of traffic management plan



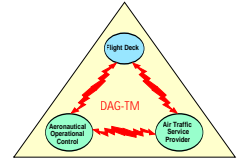
Self-spacing for Merging and In-trail Separation





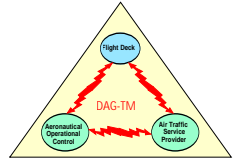
Research Plan

- **Goal: To evaluate feasibility of concept**
 - Three phases planned
- **Phase 1: Airborne management of post-merge in-trail temporal spacing**
 - Controller uses DST to set up initial sequence, monitors operations, and controls non-equipped aircraft
 - Pilots given autonomy to tighten spacing using CDTI
- **Phase 2: Airborne management of merging and spacing on structured arrival routes**
 - Controller uses DST to set up initial sequence, monitors operations, and controls non-equipped aircraft
 - Flight crew manages merge into arrival stream using CDTI
 - Self-spacing on final



Research Plan

- **Phase 3: Airborne management of merging and separation of unstructured arrival corridors**
 - Controller sets up initial sequencing and monitors airspace for conflicts
 - Structured arrival routes are replaced with arrival regions
 - Participating aircraft cross an arrival boundary and maneuver within designated arrival regions
 - Aircraft are responsible for separation assurance and remaining inside the arrival regions
 - Pilots use CDTI for merging into arrival streams based on sequence assignments provided by the controller
 - Non-participating aircraft remain on structured arrival routes and receive all clearances from the controller

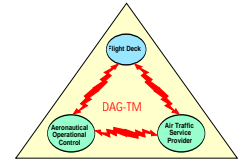


Research Issues

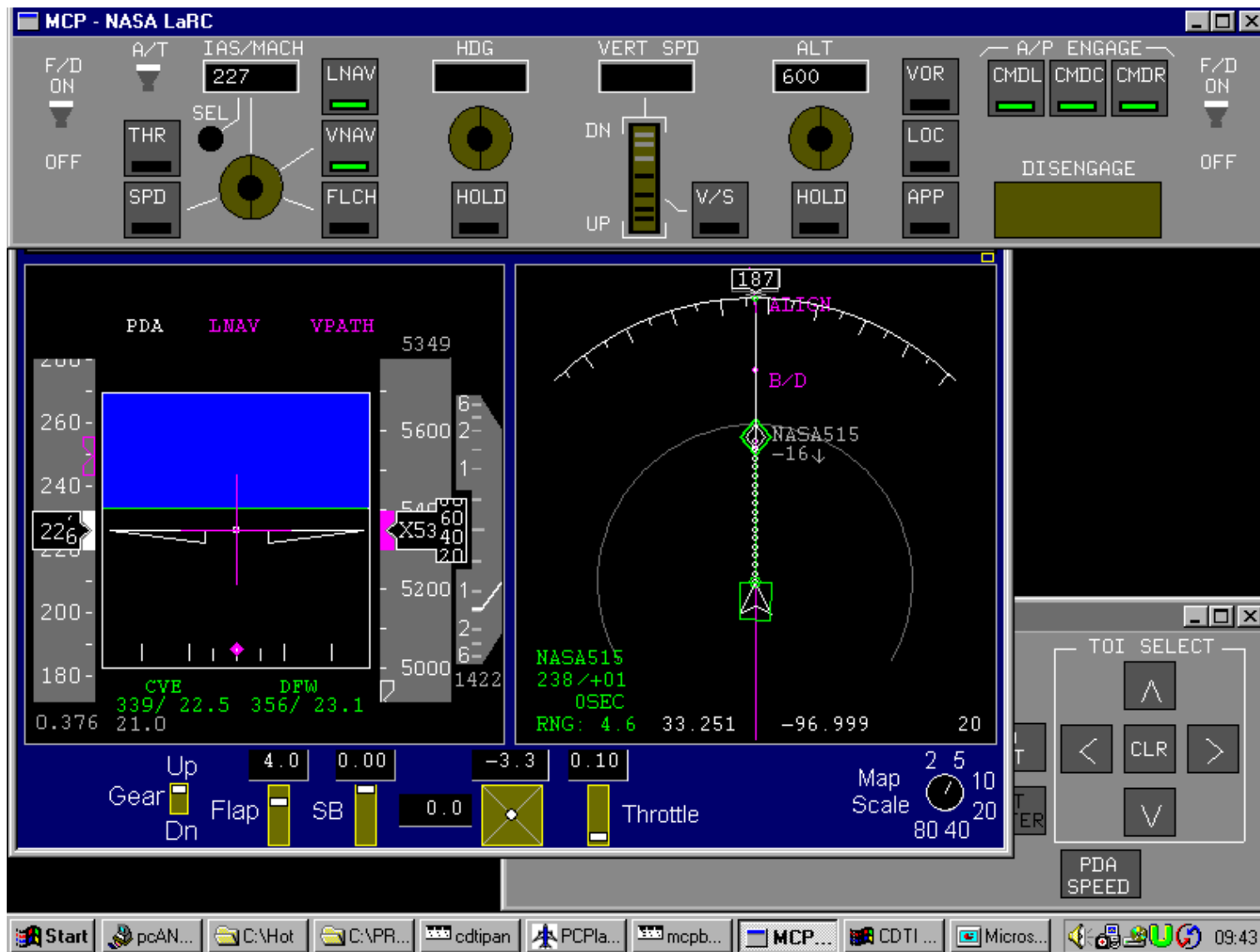
- **How to realize benefits:**
 - Pre-merge
 - Post-merge
 - Unstructured sector
- **Design of CDTI for self-merging and spacing**
 - Including CD&R logic
- **Design of controller automation**
 - Incorporation of planning tools into terminal workstation
- **Roles of pilot and controller**
 - Distributed decision making and responsibilities
 - Failure situations
 - Mixed equipage
 - Workload and other human factors issues



Self-spacing for Merging and In-trail Separation



Automation Tools: Pilot (Spacing)

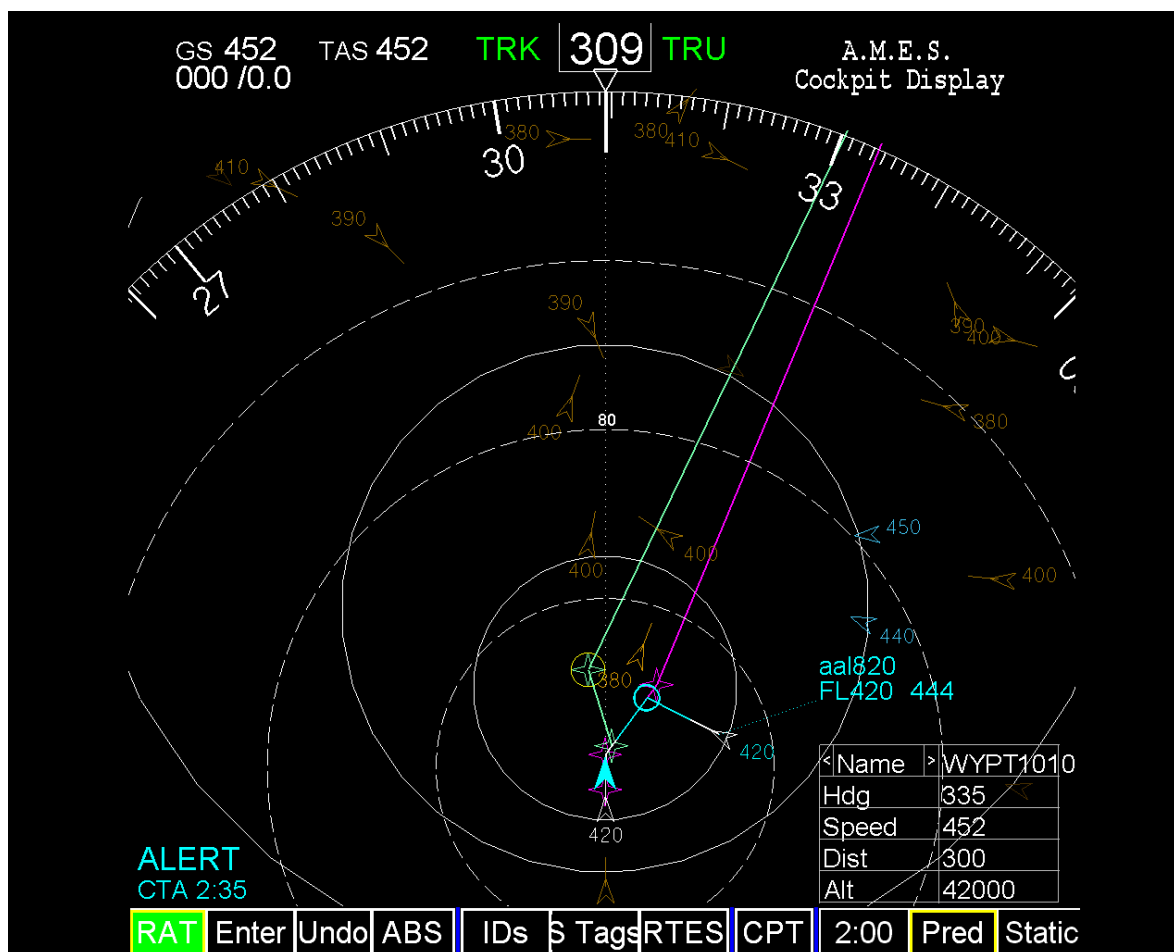




Self-spacing for Merging and In-trail Separation



Automation Tools: Pilot (Self-Separation)

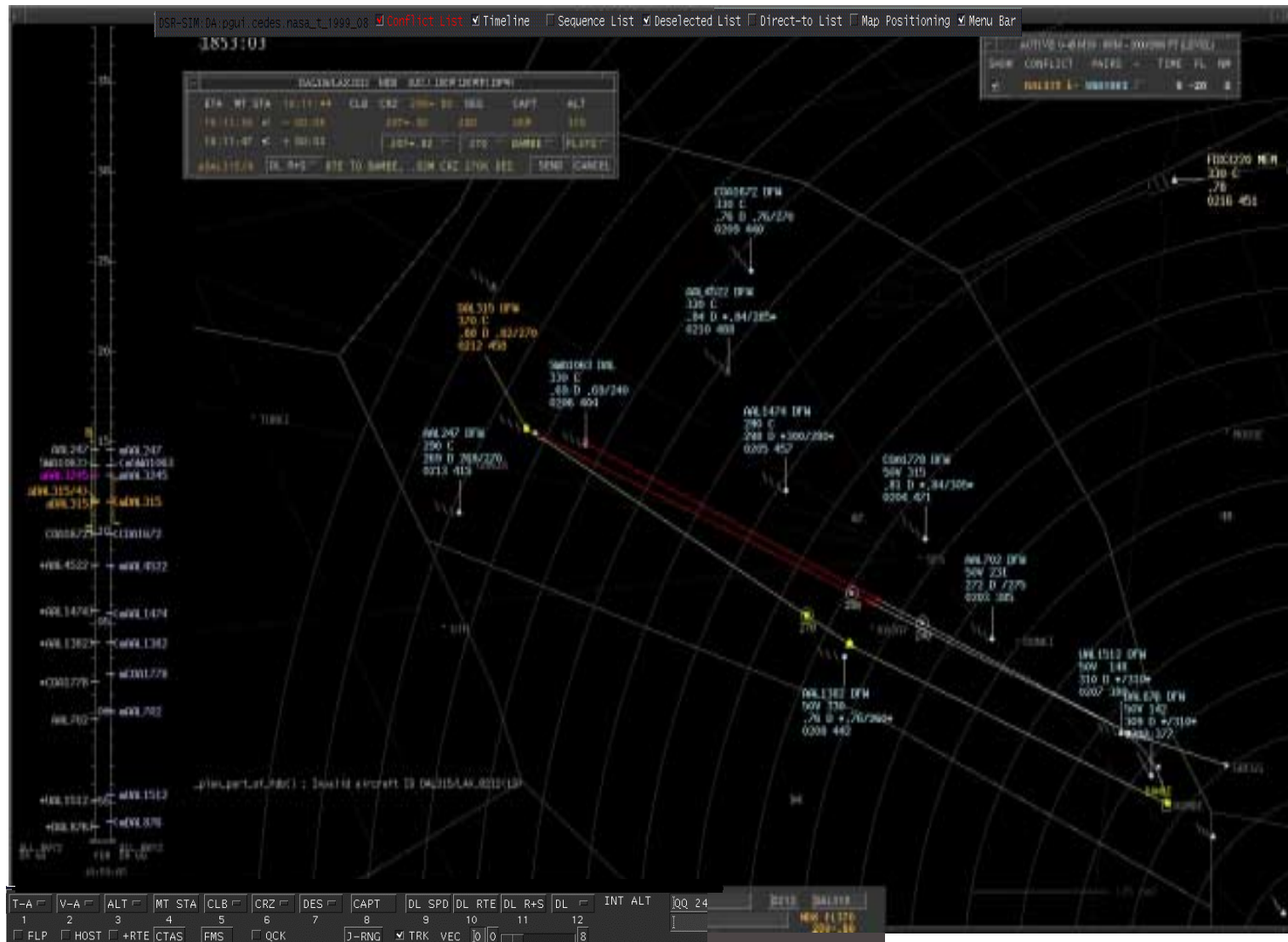


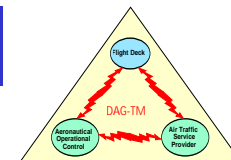


Self-spacing for Merging and In-trail Separation

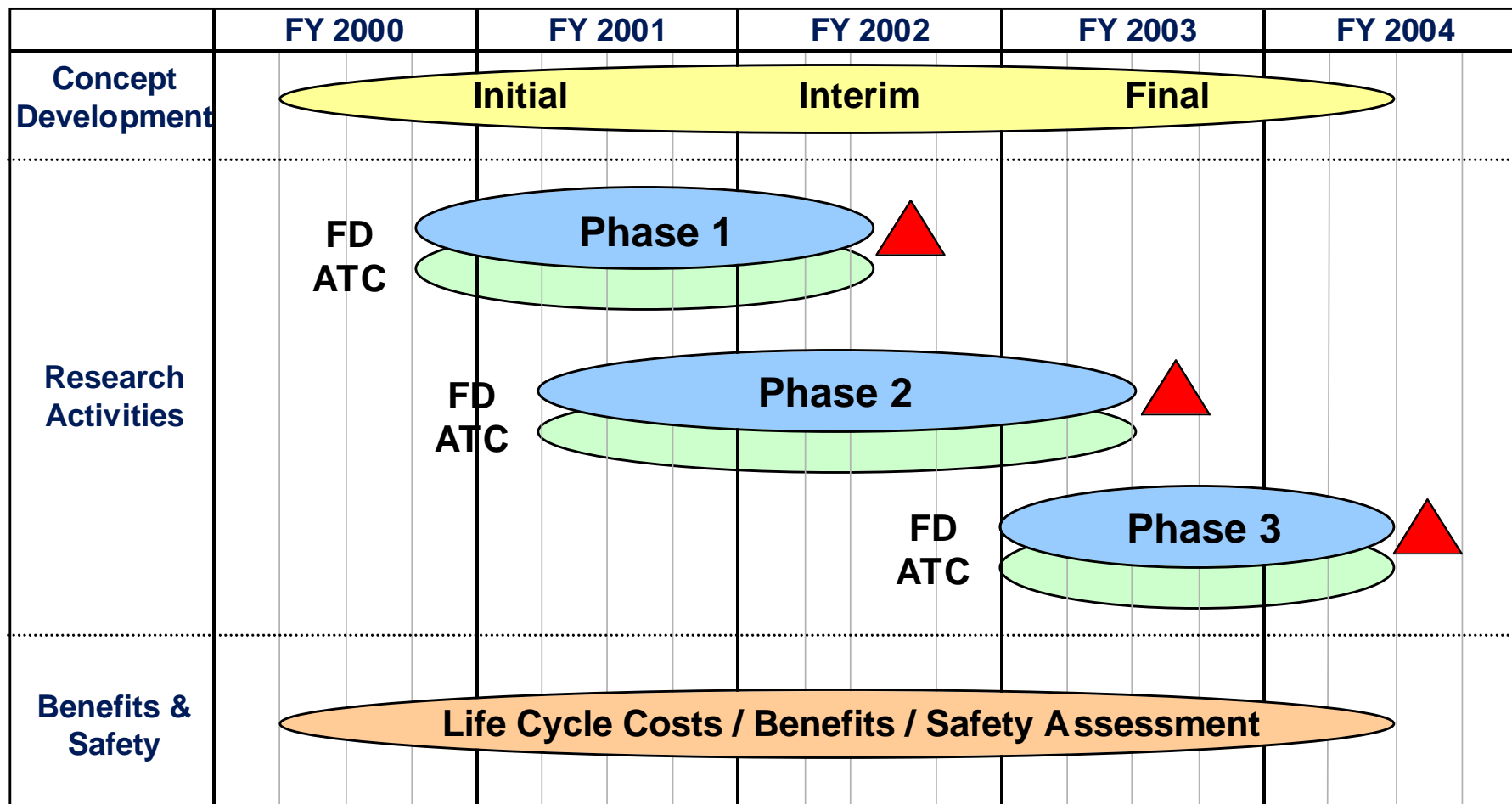


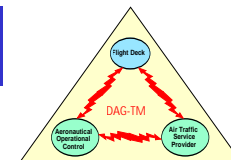
Automation Tools: Controller



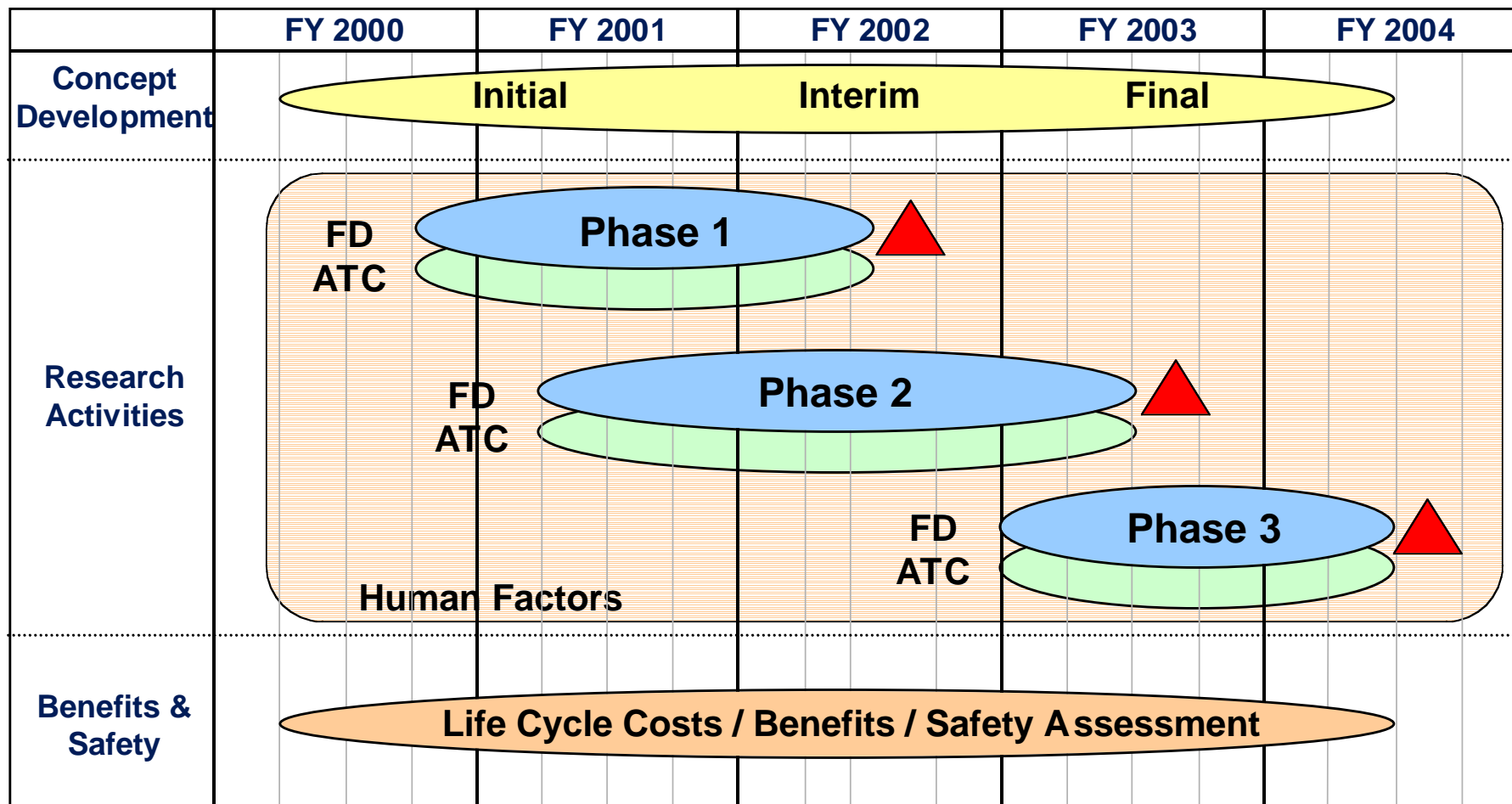


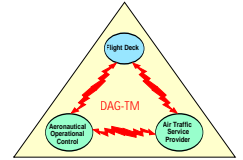
Activity Roadmap





Activity Roadmap





Presentations in this Session

- **Medium-Fidelity Flight Simulator Experiment Results**
 - Amy Pritchett - Georgia Tech
- **Cockpit Display of Traffic Information (CDTI)**
 - Oscar Olmos - MITRE
- **Approach Station Keeping Study**
 - Parimal Kopardekar - SRC/FAA